

# Open103C User Manual

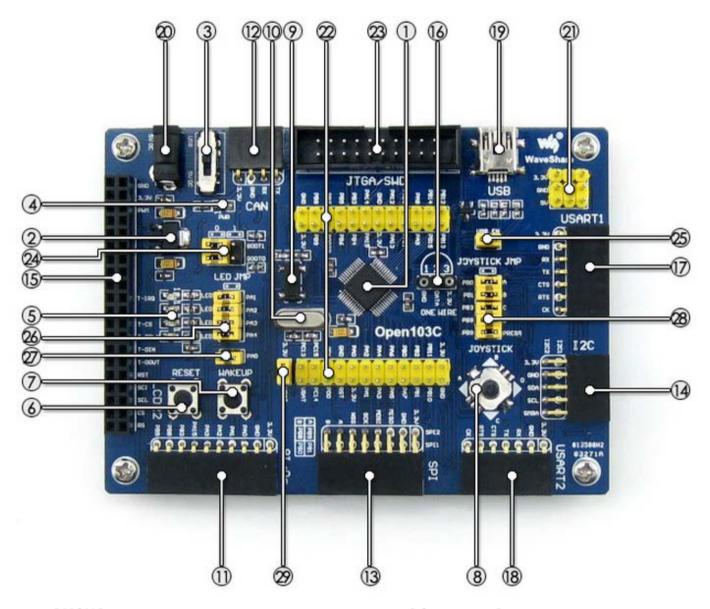
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# 1. Overview

# 1.1. What's on board



# [MCU]

#### 1. STM32F103CBT6

the high performance STM32 MCU which features:

Core: Cortex-M3 32-bit RISC;

**Operating Frequency:** 72MHz, 1.25

DMIPS/MHz:

## [ Component]

# Power supply switch 5V DC or USB

- 4. Power indicator
- 5. **LEDs**

for indicating I/O status or program debugging running state



Operating Voltage: 2-3.6V; Package: LQFP48; I/Os: 37;

Memories: 128kB Flash, 20kB RAM; Communication Interfaces: 2 x SPI, 3 x USART, 2 x I2C, 1 x USB, 1 x CAN; AD & DA converters: 22 x AD (12-bit, 1μs,

shares 10 channels);

**Debugging/Programming:** supports JTAG/SWD (serial wire debug) interfaces, supports IAP

#### 2. AMS1117-3.3

3.3V voltage regulator.

#### [Interface]

#### 11. 8 I/O Interface

easily connects to keypad, motor, etc.

#### 12. CAN interface

communicates with accessory board which features the CAN device conveniently

#### 13. SPI1 / SPI2 interface

easily connects to SPI peripherals such as FLASH (AT45DBxx), SD card, MP3, etc. convenient for connecting AD module, thanks to the SPI1 alternative AD function

#### 14. I2C1 / I2C2 interface

easily connects to I2C peripherals such as I/O expander (PCF8574), EEPROM (AT24Cxx), etc.

#### 15. LCD interface

easily connects to the touch screen LCD

#### 16. ONE-WIRE interface

easily connects to ONE-WIRE devices (TO-92 package), such as temperature sensor (DS18B20), electronic registration number (DS2401), etc.

#### 17. USART1 interface

easily connects to RS232, RS485, USB TO 232

#### 18. USART2 interface

easily connects to RS232, RS485, USB TO 232

#### 19. USB port

USB communication between board and PC

#### 6. RESET key

#### 7. User key

for I/O input test

#### 8. Joystick

for I/O input test (five positions)

#### 9. 32.768K crystal oscillator

used for internal RTC, also supports clock calibration

#### 10. 8M crystal oscillator

enables the MCU run at 72M frequency by frequency multiplication

#### [ Other interface ]

#### 20. 5V DC jack

#### 21. 5V/3.3 V power input/output

usually used for power output, or common ground with other user board

#### 22. MCU pins connector

all the MCU pins are accessible on expansion connectors for further expansion

#### 23. JTAG/SWD interface

for debugging/programming

#### [Jumper]

#### 20. Boot mode selection

for configuring the BOOT0 and BOOT1 pins

#### 21. USB enable jumper

short the jumper to enable the PC auto detection while USB connecting open the jumper to disable

#### 22. LEDs jumper

short the jumper to connect the user key to I/Os used in example code open the jumper to connect the user key to other custom pins via jumper wires

#### 23. User key jumper

short the jumper to connect the user key to I/Os used in example code open the jumper to connect the user key to other custom pins via jumper wires

#### 24. Joystick jumper



short the jumper to connect the joystick to I/Os used in example code open the jumper to connect the user key to other custom pins via jumper wires

### 25. VBAT selection jumper

short the jumper to use system power supply open the jumper to connect the VBAT to external power, such as battery



# 2. Demo

➤ KEIL MDK Version: 4.54

Programmer/Debugger: ULINK/V2

Programming/Debugging interface: SWD

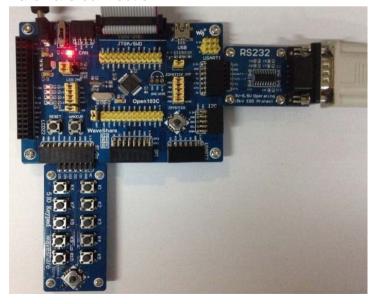
Serial port settings:

Select a proper COM port				
Baud rate	115200			
Data bits	8			
Stop bits	1			
Parity bits	None			
Flow control	None			

# 2.1. 5IOs

Demo5I/Os demo

Hardware connection



- Connect the board to 5V power via 5VDC interface
- Connect the ULINK board to the board via SWD interface
- Connect the "5IO Keypad" to the onboard 8I/Os interface (make sure the G pin on the module connects to the GND pin on the 8I/Os)
- Connect a serial port converter(RS232) to the onboard USART1 interface

Operation and result

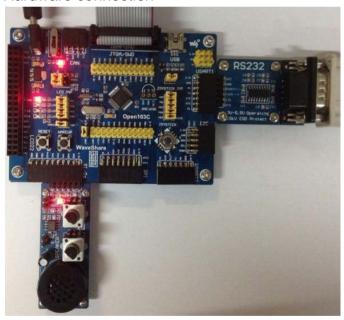


➤ The below information will be printed on the serial debugging assistant:

```
KeyValue is
KeyValue is
KeyValue is
                  -K1.
-K2.
                  -K3
KeyValue is
                  -K4
KeyValue is
KeyValue is
KeyValue is
KeyValue is
KeyValue is
KeyValue is
                  -K10.
KeyValue is
                  -Right.
KeyValue is
KeyValue is :
                  -Մթ.
KevValue is :
                  -Down.
```

### 2.2. ADC

- Overview
   ADC analog voltage acquisition demo
- Hardware connection



- Connect the board to 5V power via 5VDC interface
- Connect the ULINK board to the board via SWD interface
- Connect a serial port converter(RS232) to the onboard USART1 interface
- Connect the Analog Test Board to the board via 8I/Os interface

- Operation and result
- Rotate the potentiometer on the Analog Test Board, the below information will be printed on the serial debugging assistant (the KEY value is larger indicates that the current voltage is larger):

# 2.3. CAN-LoopBack

- Overview
   CAN demo in LoopBack mode
- ◆ Hardware connection



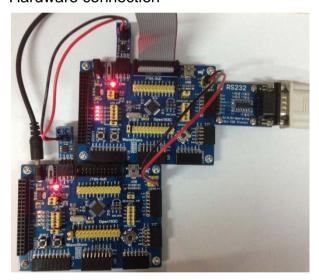
Connect the board to 5V power via 5VDC interface
Connect the ULINK2 board to the board via SWD interface
Connect a serial port converter (RS232) to the onboard USART2 interface

Operation and result

The below information will be printed on the serial debugging assistant:

### 2.4. CAN-Normal

- Overview
   CAN demo in Normal mode
- Hardware connection



- Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- Connect a serial port converter (RS232) to the onboard USART1 interface
- Two "SN65HVD230 CAN Board" are required, connect them to two Open103C board respectively

- Operation and result
  - ➤ The below information will be printed on the serial debugging assistant:

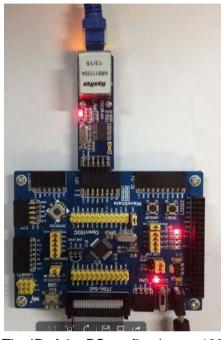


# 2.5. ENC28J60

◆ Overview

"ENC28J60 Ethernet Board" demos

♦ Hardware connection



- Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- Connect the "ENC28J60 Ethernet Board" to the onboard SPI interface, then connect it to PC through an Ethernet cable

◆ The IP of the PC configuring as 192.168.0.xxx; for example:

Configuring IP of both the PC and the module on the same network:

Right click the 【Internet】 -》 【Attribute】 -》 Click 【Local connection】 -》 Click 【Attribute】 -》 Find Internet Protocol Version4(TCP/IP V4, the following dialog box will pop up, set the appropriate IP address, subnet mask, and default gateway:

IP addresses : 192.168.0.11 Subnet Mask: 255.255.255.0 Default Gateway: 192.168.0.1

Operation and result

Open the browser; enter 192.168.0.100/888; press the Enter key:

Sent data to ENC28J60 : 0x6

[refresh]

+1

Open103C WEB test

# 2.6. GPIO LED JOYSTICK

Overview
 LED, push button, joystick demo

Hardware connection

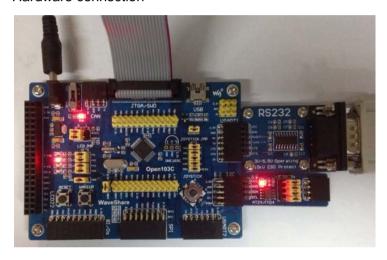


Short the LED JMP, JOYSTICK JMP, KEY JMP

Operation and result
 Push the button or joystick, the LED status should keep changing accordingly

# 2.7. I2C

- OverviewI2C EEPROM demo
- ◆ Hardware connection



- Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- Connect a serial port converter to the onboard USART1 interface
- Connect the AT24/FM24 Board to the board via I2CX interface( connect to I2C1 or I2C2 depends on the program)

- Operation and result
  - > The below information will be printed on the serial debugging assistant:

### 2.8. LCD22

- OverviewLCD demo
- ◆ Hardware connection





Operation and result
 Display image on the LCD

- > Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- Connect the "2.2inch 320x240 Touch LCD (A)" to the board

# 2.9. LCD22\_TouchPanel

- OverviewLCD demo
- ♦ Hardware connection

Connect the board to 5V power via 5VDC interface Connect the ULINK2 board to the board via SWD interface Connect the "2.2inch 320x240 Touch LCD (A)" to the board

Operation and result

Display image on the LCD



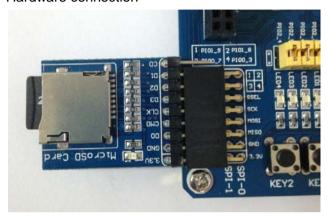
Display image on the LCD

Application
 Handheld device display



### 2.10. Micro SD

- OverviewSD FatFS demo
- ♦ Hardware connection



- Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- Connect a serial port converter to the onboard USART1 interface
- Connect the Micro SD Storage Board (with SD card) to the board via SPI1 interface

- Software configuration
- Operation and result

The below information will be printed on the serial debugging assistant:

```
SD card experiment!
Please plug in 1 GB SD card!
SD card is OK
SD card size capacity:1886 Mb
Written to the success!
Read success!
Testing is complete! All the data are correct!
```

# 2.11. NRF24L01

- Overview NRF24L01 demo
- Hardware connection



Software connection

- Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- Connect a serial port converter to the onboard USART1 interface
- Connect the NRF24L01 Board to the board via SPI interface



Two NRF24L01 are needed for this demo, the software configuring as below:

When configuring as mode of transmitting, enabled: #define T\_O\_R 1, comment out: //#define T\_O\_R 0;

When configuring as mode of receiving, enable: #define T\_O\_R 0, comment out: //#define T\_O\_R 0

Operation and result

Message will be printed on the serial debugging assistant.

# 2.12. One-Wire

Overview

One-Wire demo

◆ Hardware connection

Connect the board to 5V power via 5VDC interface

Connect the ULINK2 board to the board via SWD interface

Connect the DS18B20 to the onboard One-wire socket.

Operation and result

The below information will be printed on the serial debugging assistant:

## 2.13. RTC

Overview

RTC demo

Hardware connection

Connect the board to 5V power via 5VDC interface

Connect the ULINK2 board to the board via SWD interface

Operation and result

The below information will be printed on the serial debugging assistant:



### 2.14. SPI

- OverviewSPI demo
- Hardware connection



- Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- Connect the "AT45DBXX DataFlash Board" to the onboard SPIX interface (connect to SPI1 or SPI2 depends on the program)
- Connect a serial port converter to the onboard USART2 interface

- Software connection
  - Serial assistant configuration:

Launch the serial debugging assistant SSCOM32, choose related COM port, set baud rate as 115200, click to open it.

Operation and result

The below information will be printed on the serial debugging assistant:

# 2.15. Ucos II

- OverviewUcos ii demo
- ◆ Hardware connection

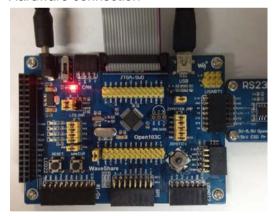




- Operation and result
   LCD displays message, LEDs keep blinking at the same time
- Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- > Short the LED jumper
- Connect the "2.2inch 320x240 Touch LCD (A)" to the board

# 2.16. USB-JoyStick Mouse

- OverviewUSB mouse demo
- ◆ Hardware connection



- ◆ Software configuration
- Operation and result

An USB device will appear on the PC device manager:



Control the computer cursor by joystick

- Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- Connect the board to the PC through USB cable

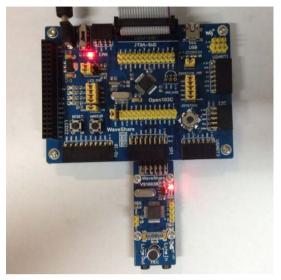
# 2.17. VS1003B

Overview



### MP3 record/play demo

♦ Hardware connection



- Connect the board to 5V power via 5VDC interface
- Connect the ULINK2 board to the board via SWD interface
- Connect the "VS1003B MP3 Board" to the onboard SPI1 interface

- Operation and result
  - -VS1003 (GPIO): P0 LED keep blinking
  - ·VS1003 (line in): can hear music from the PC
  - ·VS1003 (line out): can hear music from the MCU FLASH
  - ·VS1003 (record): can hear sound from the microphone

# 3. Revision history

Version	Description	Date	Author
V1.0	Initial revision	2014/05/17	Waveshare team